| Mission 2 (Introduction to | CodeBot) |
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| What should you do before handling the CodeBot? | a) Clean it with wet wipes b) Rub your feet on carpet c) Touch some grounded metal d) Put in batteries |
| What lets your computer communicate with the CodeBot? | a) Peripheralsb) The motorsc) import botcored) The USB cable |
| What is the computer science definition of "PERIPHERAL"? | a) The "brain" of the computer that executes code b) A 3D environment that lets you see the robot move in a virtual world c) A device that gives input or output to a computer d) A computer on wheels with built-in sensors |
| What is the computer science definition of "CODE"? | a) Instructions to the computer b) A way to encode messages c) Problems in a program that need to be fixed d) A computer on wheels with built-in sensors |
| What is the computer science definition of "IMPORT"? | a) Instructions to the computer b) A command that provides access to a module of built-in functions c) Devices that give input or output to a computer d) A computer on wheels with built-in sensors |
| Python is case sensitive. This means: | a) "Number" is the same as "number" b) "Number" is not the same as "number" c) Punctuation isn't important d) Capitalization doesn't matter |
| What code will let you access LEDs functions? | a) from botcore b) import leds c) from botcore import leds d) from botcore access leds |
| What code will turn on the far-right led? | a) leds.user_num(0, True) b) leds.user_num(7, True) c) leds.user(num_1, True) d) user.leds_num(0, False) |
| What code will turn off the far-left led? | a) leds.user_num(0, False) b) leds.user_num(7, False) c) leds.user(num_7, False) d) user.leds_num(7, True) |
| Boolean values are: | a) On or Off b) 0 or 1 c) True or False d) Numbered for leds |

| Mission 3 Time and Motion (Objectives 1-6) | | |
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| What is the computer science definition of "LITERAL"? | a) A name to data that can then be used in a program b) An actual value, like 1 or 1.5 c) Something that is exact d) Data that is passed to a function when it is called | |
| What is the computer science definition of "VARIABLE"? | a) A name to data that can then be used in a program b) An actual value, like 1 or 1.5 c) Something that can change d) Data that is passed to a function when it is called | |
| What is the computer science definition of "ARGUMENT"? | a) A name to data that can then be used in a program b) An actual value, like 1 or 1.5 c) When programmers collaborate d) Data that is passed to a function when it is called | |
| What is the computer science definition of "BINARY"? | a) A choice between two options b) A way to count with numbers c) The two states of electric circuits: On or Off d) A group of 8 bits, used in programming | |
| What is the computer science definition of "BYTE"? | a) A group of 8 binary digits b) A way to count with numbers c) The two states of electric circuits: On or Off d) Chunking programming code into smaller parts | |
| When you use the debugger the line of code that is highlighted: 4 | a) Will run the next time you press STEP b) Ran the last time you pressed STEP c) Is currently running d) Will stop the program | |
| Why would you add a sleep() command after turning on an LED? | a) So it will turn on b) So you can see it turn on before anything else happens c) To give the LED time to cool off d) You shouldn't add it because it will cause an error | |
| What does this statement do? from time import sleep | a) Gives the code access to the sleep function from the time module b) Gives the code access to the time function from the sleep module c) Is necessary or the program won't run d) Allows the code to sleep from time to time | |
| This statement will: sleep(0.75) | a) Pause the program for .75 milliseconds b) Pause the program for .75 seconds c) Turn off the LED for .75 seconds d) Cause an error | |

Which LED does the following code turn ON:

leds.user(0b00000010)

- a) User LED 2
- b) Line Sensor LED 2
- c) User LED 1
- d) Line Sensor LED 7

| Mission 3 Time and Motion (Objectives 7-9) | | |
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| What is the computer science definition of "COMMENTS"? | a) Notes in the code about what you are doing b) Feedback from another programmer c) Required statements at the top of your code d) Imports the modules so you can use built-in functions | |
| What is the computer science definition of "ALGORITHM"? | a) Adding blank lines and spaces to your code b) Chunking your code into bite-sized pieces c) A precise sequence of step-by-step instructions d) Accessing built-in functions | |
| What are two ways to add readability to your code: | a) Algorithms and divide-and-conquer b) Importing modules and using variables c) Binary and Boolean d) Comments and whitespace | |
| What does this code do? delay = 1 | a) Sets the sleep to 1 b) Pauses the program execution for 1 second c) Puts the CodeBot to sleep for 1 second d) Assigns the value 1 to the variable "delay" | |
| What does this code do? sleep(delay) | a) Assigns the variable "sleep" the value "delay" b) Pauses the program execution for "delay" seconds c) Puts CodeBot to sleep for "delay" seconds d) Causes an error | |
| What line of code will import all built-in functions from a module or library? | import * c) import from botcore * b) from botcore import * d) from botcore | |
| What code will turn on the motors? | a) motors.enable(True) c) enable.motors(False) b) motors.on(True) d) motors.turn_on() | |
| What code will turn off the motors | a) disable.motors(True) | |
| What will this code do? motors.run(LEFT, 50) motors.run(RIGHT, -50) | a) Move the 'bot forward b) Make the 'bot turn c) Make the 'bot go backward d) Cause the 'bot to stop | |
| What will this code do? motors.run(LEFT, 50) motors.run(RIGHT, 50) | a) Move the 'bot forward b) Make the 'bot turn c) Make the 'bot go backward d) Cause the 'bot to stop | |

| Mission 3 Time and Motion (Objectives 10-11) | | |
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| What is the computer science definition of "BRANCHING"? | a) A Boolean value; either True or False, often the result of a comparison b) Decision points in code; taking a different path depending on a condition c) A way to structure blocks of code by offsetting the block four spaces d) A precise sequence of step-by-step instructions | |
| What is the computer science definition of "CONDITION"? | a) A Boolean value; either True or False, often the result of a comparison b) Decision points in code; taking a different path depending on a Boolean c) A way to structure blocks of code by offsetting the block four spaces d) A precise sequence of step-by-step instructions | |
| What happens if Button-O was pressed? if buttons.was_pressed(0): leds.user_num(0, True) elif buttons.was_pressed(1): leds.user_num(7, True) else: leds.user(0b000000000) | a) The user LED 0 turns on b) All user LEDs turn off c) The user LED 7 turns on d) LED 0 turns on, then LED 7 turns on, then they both turn off | |
| What happens if Button-1 was pressed? if buttons.was_pressed(0): leds.user_num(0, True) elif buttons.was_pressed(1): leds.user_num(7, True) else: leds.user(0b000000000) | a) The user LED 0 turns on b) All user LEDs turn off c) The user LED 7 turns on d) LED 0 turns on, then LED 7 turns on, then they both turn off | |
| What happens if no button was pressed? if buttons.was_pressed(0): leds.user_num(0, True) elif buttons.was_pressed(1): leds.user_num(7, True) else: leds.user(0b000000000) | a) The user LED 0 turns on b) All user LEDs turn off c) The user LED 7 turns on d) LED 0 turns on, then LED 7 turns on, then they both turn off | |
| What happens if Button-O was pressed? if buttons.was_pressed(0): motors.enable(True) else: motors.enable(False) | a) The motors are turned off b) The motors are turned on c) The motors are turned on and then off d) Nothing happens | |
| What happens if Button-1 was pressed? if buttons.was_pressed(0): motors.enable(True) else: motors.enable(False) | a) The motors are turned off b) The motors are turned on c) The motors are turned on and then off d) Nothing happens | |

| What happens if no button was pressed? if buttons.was_pressed(0): motors.enable(True) else: motors.enable(False) | a) The motors are turned off b) The motors are turned on c) The motors are turned on and then off d) Nothing happens |
|---|---|
| What happens if Button-O was pressed? if buttons.was_pressed(1): leds.user(0b11111111) | a) All user LEDs turn on b) All user LEDs turn off c) Nothing happens d) All LEDS turn on and then off |
| What happens if Button-1 was pressed? if buttons.was_pressed(1): leds.user(0b11111111) | a) All user LEDs turn on b) All user LEDs turn off c) Nothing happens d) All LEDS turn on and then off |

| Unit 1 Vocabulary Review/Test (Missions 1-3: All questions are the computer science definition of) (compilation of 13 terms from previous reviews, plus two more terms – same terms for review and test) | |
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| Peripheral | a) The "brain" of the computer that executes code b) A 3D environment that lets you see the robot move in a virtual world c) A device that gives input or output to a computer d) A computer on wheels with built-in sensors |
| LED | a) The "brain" of the computer that executes code b) A device that gives input to a computer c) A computer on wheels with built-in sensors d) tiny and efficient electronic components that produce light |
| Code | a) Instructions to the computer b) A way to encode messages c) Problems in a program that need to be fixed d) A computer on wheels with built-in sensors |
| Import | a) Instructions to the computer b) A command that provides access to a module of built-in functions c) Devices that give input or output to a computer d) A computer on wheels with built-in sensors |
| CPU | a) The "brain" of the computer that executes code b) A device that gives input to a computer c) A computer on wheels with built-in sensors d) tiny and efficient electronic components that produce light |
| Literal | a) A name to data that can then be used in a program b) An actual value, like 1 or 1.5 c) Something that is exact d) Data that is passed to a function when it is called |

| Variable | a) A name to data that can then be used in a program b) An actual value, like 1 or 1.5 c) Something that can change d) Data that is passed to a function when it is called |
|-----------|--|
| Argument | a) A name to data that can then be used in a program b) An actual value, like 1 or 1.5 c) When programmers collaborate d) Data that is passed to a function when it is called |
| Boolean | a) On or Off b) 0 or 1 c) True or False d) Numbered for leds |
| Binary | a) A choice between two options b) A way to count with numbers c) The two states of electric circuits: On or Off d) A group of 8 bits, used in programming |
| Byte | a) A group of 8 binary digits b) A way to count with numbers c) The two states of electric circuits: On or Off d) Chunking programming code into smaller parts |
| Comments | a) Notes in the code about what you are doing b) Feedback from another programmer c) Required statements at the top of your code d) Imports the modules so you can use built-in functions |
| Algorithm | a) Adding blank lines and spaces to your code b) Chunking your code into bite-sized pieces c) A precise sequence of step-by-step instructions d) Accessing built-in functions |
| Branching | a) A Boolean value; either True or False, often the result of a comparison b) Decision points in code; taking a different path depending on a condition c) A way to structure blocks of code by offsetting the block four spaces d) A precise sequence of step-by-step instructions |
| Condition | a) A Boolean value; either True or False, often the result of a comparison b) Decision points in code; taking a different path depending on a Boolean c) A way to structure blocks of code by offsetting the block four spaces d) A precise sequence of step-by-step instructions |

| Unit 1 Concepts and Coding Test (Missions 1-3) / (review questions with modifications) | | |
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| Python is case sensitive. This means: | a) Capitalization doesn't matter b) Punctuation isn't important c) "Delay" is the same as "delay" d) "Delay" is not the same as "delay" | |
| What are two ways to add readability to your code: | a) Comments and whitespace b) Algorithms and divide-and-conquer c) Binary and Boolean d) Importing modules and using variables | |
| What line of code will import all built-in functions from a module or library? | from botcore c) from botcore import * b) import from botcore * d) import * | |
| What code will turn on the far-left user LED? | a) leds.user_num(0, True) b) leds.user_num(7, True) c) leds.user(num_8, True) d) user.leds_num(7, True) | |
| What code will turn off the far-right user LED? | a) leds.user_num(0, False) b) leds.user_num(1, False) c) leds.user(num_8, False) d) user.leds_num(7, False) | |
| This statement will: sleep(1.25) | a) Cause an error b) Pause the program for 1.25 milliseconds c) Pause the program for 1.25 seconds d) Turn on the LED for 1.25 seconds | |
| Which LED does the following code turn ON: leds.user(0b00001000) | a) User LED 2 b) User LED 3 c) User LED 4 d) User LED 5 | |
| What does this code do? delay = 0.25 | a) Pauses the program execution for 0.25 seconds b) Sets the sleep to 0.25 c) Puts the CodeBot to sleep for 0.25 seconds d) Assigns the value 0.25 to the variable "delay" | |
| What does this code do? sleep(delay) | a) Puts CodeBot to sleep for "delay" seconds b) Assigns the value "delay" to the variable "sleep" c) Pauses the program execution for "delay" seconds d) Causes an error | |
| What code will turn on the motors? | a) enable.motors(True) c) motors.enable(True) b) motors.turn_on() d) motors.on(True) | |
| What code will turn off the motors | a) motors.enable(False) c) motors.on(False) b) motors.turn_off() d) disable.motors(True) | |

What will this code do? a) Move the 'bot forward b) Make the 'bot turn motors.run(LEFT, -50) c) Make the 'bot go backward motors.run(RIGHT, -50) d) Cause the 'bot to stop What will this code do? a) Move the 'bot forward b) Make the 'bot turn motors.run(LEFT, -50) c) Make the 'bot go backward motors.run(RIGHT, 50) d) Cause the 'bot to stop What happens if Button-0 a) The 'bot moves forward was pressed? b) The motors are turned off c) The motors are turned on if buttons.was pressed(0): motors.enable(True) d) The motors are turned on, the 'bot moves forward, and then the elif buttons.was pressed(1): motors are turned off motors.enable(False) motors.run(LEFT, 50) motors.run(RIGHT, 50) What happens if Button-1 a) The 'bot moves forward was pressed? b) The motors are turned off c) The motors are turned on if buttons.was pressed(0): d) The motors are turned on, the 'bot moves forward, and then the motors.enable(True) elif buttons.was pressed(1): motors are turned off motors.enable(False) motors.run(LEFT, 50) motors.run(RIGHT, 50) What happens if no button a) The 'bot moves forward was pressed? b) The motors are turned off c) The motors are turned on if buttons.was_pressed(0): motors.enable(True) d) The motors are turned on, the 'bot moves forward, and then the elif buttons.was_pressed(1): motors are turned off motors.enable(False) motors.run(LEFT, 50) motors.run(RIGHT, 50) What happens if Button-0 a) A user LED turns on was pressed? b) A user LED turns on and then turns off c) A user LED turns off if buttons.was pressed(0): leds.user_num(3, True) d) Nothing happens sleep(1) leds.user_num(3, False) What happens if Button-1 a) A user LED turns on was pressed? b) A user LED turns on and then turns off c) A user LED turns off if buttons.was pressed(0): leds.user num(3, True) d) Nothing happens sleep(1) leds.user_num(3, False)

What happens if Button-1 was pressed? if buttons.was_pressed(1)

if buttons.was_pressed(1):
 leds.ls(0b11111)
 leds.user(0b00000000)
else:
 leds.ls(0b00000)
 leds.user(0b11111111)

- a) Line sensor LEDs are turned on and user LEDs are turned off
- b) User LEDs are turned on and line sensor LEDs are turned off
- c) User LEDs and line sensor LEDs are turned on and then off
- d) Nothing happens

What happens if no button was pressed?

```
if buttons.was_pressed(1):
    leds.ls(0b11111)
    leds.user(0b00000000)
else:
    leds.ls(0b00000)
    leds.user(0b11111111)
```

- a) Line sensor LEDs are turned on and user LEDs are turned off
- b) User LEDs are turned on and line sensor LEDs are turned off
- c) User LEDs and line sensor LEDs are turned on and then off
- d) Nothing happens